

# AN AUGMENTATION METHOD FOR MULTILEVEL ANALYSIS

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ABSTRACT. Dodo

## 1. INTRODUCTION

## 2. MODEL

The micro-model is

$$(1a) \quad \underline{y}_j = X_j \underline{b}_j + \underline{\epsilon}_j,$$

and the macro-model is

$$(1b) \quad \underline{b}_j = Z_j \gamma + \underline{\delta}_j,$$

which implies

$$(2) \quad \underline{y}_j = X_j Z_j \gamma + X_j \underline{\delta}_j + \underline{\epsilon}_j.$$

Here  $\underline{y}_j$  has  $n_j$  elements,  $X_j$  is  $n_j \times p$ , and  $Z_j$  is  $p \times q$ . We suppose, in addition, that the disturbances  $(\underline{\epsilon}_j, \underline{\delta}_j)$  are i.i.d. and satisfy

$$(3) \quad \begin{bmatrix} \underline{\epsilon}_j \\ \underline{\delta}_j \end{bmatrix} \sim \mathcal{N} \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma^2 \mathcal{I} & 0 \\ 0 & \Omega \end{bmatrix} \right).$$

It follows that

$$(4) \quad \underline{y}_j \sim \mathcal{N}(X_j Z_j \gamma, X_j \Omega X_j' + \sigma^2 \mathcal{I}),$$

and the  $\underline{y}_j$  are independent.

## 3. LIKELIHOOD

The negative log-likelihood, except for irrelevant constants, is

$$(5) \quad \mathcal{L} = \sum_{j=1}^m \log |X_j \Omega X_j' + \sigma^2 \mathcal{I}| + \sum_{j=1}^m (y_j - X_j Z_j \gamma)' [X_j \Omega X_j' + \sigma^2 \mathcal{I}]^{-1} (y_j - X_j Z_j \gamma).$$

This can be simplified considerably.

First, we write  $y_j$  in the form

$$(6) \quad y_j = X_j b_j + r_j,$$

where  $r_j' X_j = 0$ . This is always possible by taking  $b_j$  equal to a set of least-squares regression coefficients in the regression of  $y_j$  on  $X_j$ . If  $X_j$  is of full column rank  $p$ , then this decomposition is actually unique. Let us assume full rank for the time being.

Second, we can also write

$$(7) \quad X_j \Omega X_j' + \sigma^2 \mathcal{I} = X_j (\Omega + \sigma^2 (X_j' X_j)^{-1}) X_j' + \sigma^2 Q_j,$$

with  $Q_j = \mathcal{I} - X_j (X_j' X_j)^{-1} X_j'$ .

It follows from (6) and (7) that

$$(8a) \quad (y_j - X_j Z_j \gamma)' [X_j \Omega X_j' + \sigma^2 \mathcal{I}]^{-1} (y_j - X_j Z_j \gamma) = (b_j - Z_j \gamma)' (\Omega + \sigma^2 (X_j' X_j)^{-1})^{-1} (b_j - Z_j \gamma) + \sigma^{-2} r_j' r_j,$$

and

$$(8b) \quad \log |X_j \Omega X_j' + \sigma^2 \mathcal{I}| = \log |X_j' X_j| + \log |\Omega + \sigma^2 (X_j' X_j)^{-1}| + (n_j - p) \log \sigma^2.$$

Letting

$$(9) \quad W_j \triangleq \Omega + \sigma^2 (X_j' X_j)^{-1}$$

and

$$(10) \quad s_j^2 \triangleq \frac{1}{n_j - p} r_j' r_j$$

we see that

$$(11) \quad \mathcal{L} = \sum_{j=1}^m \log |X_j' X_j| + \sum_{j=1}^m \{ \log |W_j| + (b_j - Z_j \gamma)' W_j^{-1} (b_j - Z_j \gamma) \} + \sum_{j=1}^m (n_j - p) \{ \log \sigma^2 + \frac{s_j^2}{\sigma^2} \}$$

#### 4. THE BALANCED CASE

The multilevel design is balanced if the  $n_j$  are the same for all  $j$  and if the  $X_j' X_j$  are the same for all  $j$  as well. Balanced designs occur typically in repeated measures or growth curve experiments, in which there are no missing data. Then the columns of the  $X_j$  are simple functions (for instance monomials) of time, and thus if the time-points for all individuals are the same, the  $X_j$  are the same.

Suppose  $n$  is the common value of the  $n_j$ ,  $X' X$  is the common value of  $X_j' X_j$ , and  $W$  is the common value of the  $W_j$ . It becomes easy to give simple expressions for the maximum likelihood estimates of the parameters.

$$(12a) \quad \hat{\sigma}^2 = \frac{1}{m} \sum_{j=1}^m s_j^2,$$

$$(12b) \quad \hat{W} = \frac{1}{m} \sum_{j=1}^m (b_j - Z_j \hat{\gamma})(b_j - Z_j \hat{\gamma})',$$

$$(12c) \quad \hat{\gamma} = \left( \sum_{j=1}^m Z_j' \hat{W}^{-1} Z_j \right)^{-1} \sum_{j=1}^m Z_j' \hat{W}^{-1} b_j.$$

The maximum likelihood estimate of  $\Omega$  is then simply

$$(12d) \quad \hat{\Omega} = \hat{W} - \hat{\sigma}^2 X' X.$$

Observe that it is possible that  $\hat{\Omega}$  is not positive semi-definite. We could, of course, impose restrictions to exclude this unhappy event, we could also take it as an important diagnostic, because it indicates failure of the model.

The equations (12) can be solved in a very straightforward way by *block relaxation*. We start with an estimate of  $\gamma$ , then use (12b) to find the optimal  $W$  for this  $\gamma$ , then use (12c) to find a new  $\gamma$ , optimal for the current  $W$ , and so on. The computations in each step are very simple,

and the interpretation of the computations is simple as well.  $\hat{\sigma}^2$  is just the variance of the first order residuals,  $\hat{W}$  is the variance-covariance matrix of the second order residuals, and  $\hat{\gamma}$  is the two step estimator of the fixed regression coefficients, suitably weighted.

## 5. DEALING WITH IMBALANCE

If the  $X_j$  are different, then the  $W_j$  are different, and solving the likelihood equations is no longer simple. But we can use a classical trick, sometimes called *augmentation*, to balance the data. Suppose  $C$  is a matrix of order  $p$ , satisfying  $C \succcurlyeq X_j'X_j$  in the Loewner sense for all  $j$ . Thus  $C - X_j'X_j$  is positive semi-definite. This means that we can find a  $p \times p$  matrix  $H_j$  such that  $H_j'H_j = C - X_j'X_j$ . Augmentation works by adding the  $p$  rows of  $H_j$  as additional pseudo-observations to  $X_j$ . Clearly the augmented  $X_j$ , say  $\tilde{X}_j$ , now satisfies  $\tilde{X}_j'\tilde{X}_j = C$ .

Because we have augmented  $X_j$  we also need to augment  $y_j$ . The  $p$  additional elements of  $y_j$ , let's call them  $g_j$ , just become additional parameters we have to minimize over. We just use

$$(13) \quad \mathcal{L} = \sum_{j=1}^m \log |X_j\Omega X_j' + \sigma^2\mathcal{I}| + \sum_{j=1}^m (\tilde{y}_j - \tilde{X}_j Z_j \gamma)' [\tilde{X}_j \Omega \tilde{X}_j' + \sigma^2 \mathcal{I}]^{-1} (\tilde{y}_j - \tilde{X}_j Z_j \gamma),$$

which now must be minimized over  $\gamma$ ,  $\sigma^2$ ,  $\Omega$ , and the unknown elements of the  $\tilde{y}_j$ . Minimizing over these unknown elements is real easy, we just set

$$(14) \quad g_j = H_j Z_j \hat{\gamma}$$

in an additional substep of the iteration. The  $g_j$  are used to compute the corresponding  $\tilde{b}_j$ , with

$$(15) \quad \tilde{b}_j = C^{-1} \{ (X_j'X_j)b_j + (C - X_j'X_j)Z_j\hat{\gamma} \}.$$

Since choosing the optimal  $g_j$  by (14) makes the corresponding residuals zero, augmenting does not change the sum of squares of the residuals, i.e. does not change  $s_j^2$ . Also, we see from (15) that we never really need  $H_j$  and  $g_j$ . All that is needed is  $C$ . Observe that the theory in this section can also be applied if one or more of the  $X_j'X_j$  are singular, as long as we choose  $C$  to be nonsingular.

It seems clear that  $C$  should be chosen as small as possible from those matrices satisfying the condition  $C \succcurlyeq X_j'X_j$ . A  $C$  which is very large

leads to  $b_j \approx Z_j \hat{\gamma}$ , which means there will be almost no change from one iteration to the next. Convergence will be slow. The obvious choice

$$(16) \quad C = \sum_{j=1}^m X_j' X_j$$

may not be very good, and a more careful choice may be called for in many cases.

## 6. BALANCING

Consider the problem of minimizing  $C$  under the condition  $C \succcurlyeq X_j' X_j$ .

## 7. ANALYSIS OF BOUNDARY CASES

### 8. RELATIONSHIP WITH EM

### 9. RELATIONSHIP WITH EB

### 10. RESTRICTIONS ON $\Omega$

Our developments so far depend critically on balance in the design, or on balance introduced by augmentation, but also on the fact that  $\Omega$  can be any positive semi-definite matrix. If  $\Omega$  is restricted in some form or another, then we cannot find it simply by using (??), and we have to impose the restrictions directly.

Most commonly, we write  $\Omega$  in the form

$$(17) \quad \Omega = \sum_{k=1}^{\ell} \omega_k A_k,$$

i.e.  $\Omega$  must be a weighted sum of known matrices.

## 11. MULTILEVEL BLOCK STRUCTURE

In many classical multilevel situations, the matrices  $Z_j$  are of the form

$$(18) \quad Z_j = \begin{bmatrix} z_j' & 0 & \dots & 0 \\ 0 & z_j' & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & z_j' \end{bmatrix},$$

i.e.  $Z_j$  is the direct sum of  $p$  copies of a vector  $z_j$ , with, say,  $v$  elements. If we have this additional structure, then the likelihood equations can be written more compactly in matrix notation.

Clearly in this case  $Z_j\gamma$  can be written as  $\Gamma z_j$ , with  $\Gamma$  an  $p \times v$  matrix. Collecting all the  $b_j$  and  $z_j$  in an  $p \times m$  matrix  $B$  and a  $v \times m$  matrix  $Z$  we find

$$(19a) \quad \hat{W} = (B - \Gamma Z)(B - \Gamma Z)',$$

and

$$(19b) \quad \hat{\Gamma} = (W^{-1} \otimes ZZ')^{-1}W^{-1}BZ'$$

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